Package 'stokes'

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Type Package

Title The Exterior Calculus

Version 1.1-1

Depends spray (>= 1.0-18)

Suggests knitr,
Deriv,
testthat,
markdown,
rmarkdown,
emulator

VignetteBuilder knitr

Imports permutations (>= 1.0-4), partitions, methods, mathjaxr, disordR (>= 0.0-8)

Maintainer Robin K. S. Hankin <hankin.robin@gmail.com>

Description Provides functionality for working with tensors, alternating tensors, wedge products, Stokes's theorem, and related concepts from the exterior calculus. Functionality for Grassman algebra is provided. The canonical reference would be: M. Spivak (1965, ISBN:0-8053-9021-9) ``Calculus on Manifolds''.

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URL https://github.com/RobinHankin/stokes

BugReports https://github.com/RobinHankin/stokes/issues

RdMacros mathjaxr

R topics documented:

`stokes-package` *The Exterior Calculus*

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Details

The DESCRIPTION file:

Package:	stokes
Type:	Package
Title:	The Exterior Calculus
Version:	1.1-1
Depends:	spray (>= 1.0-18)
Suggests:	knitr, Deriv, testthat, markdown, rmarkdown, emulator
VignetteBuilder:	knitr
Imports:	permutations (>= 1.0-4), partitions, methods, mathjaxr, disordR (>= 0.0-8)
Authors@R:	person(given=c("Robin", "K. S."), family="Hankin", role = c("aut","cre"), email="hankin.robin@gma
Maintainer:	Robin K. S. Hankin <hankin.robin@gmail.com>
Description:	Provides functionality for working with tensors, alternating tensors, wedge products, Stokes's theorem
License:	GPL-2
URL:	https://github.com/RobinHankin/stokes
BugReports:	https://github.com/RobinHankin/stokes/issues
RdMacros:	mathjaxr
Author:	Robin K. S. Hankin [aut, cre] (<https://orcid.org/0000-0001-5982-0415>)

Index of help topics:

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consolidate	Various low-level helper functions
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inner	Inner product operator
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zeroform	Zero tensors and zero forms

Generally in the package, arguments that are k-forms are denoted `K`, k-tensors by `U`, and spray objects by `S`. Multilinear maps (which may be either k-forms or k-tensors) are denoted by `M`.

Author(s)

NA

Maintainer: Robin K. S. Hankin <hankin.robin@gmail.com>

References

- J. H. Hubbard and B. B. Hubbard 2015. *Vector calculus, linear algebra and differential forms: a unified approach*. Ithaca, NY.
- M. Spivak 1971. *Calculus on manifolds*, Addison-Wesley.

See Also

spray

Examples

```
## Some k-tensors:
U1 <- as.ktensor(matrix(1:15,5,3))
U2 <- as.ktensor(cbind(1:3,2:4),1:3)

## Coerce a tensor to functional form, here mapping V^3  -> R (here V=R^15):
as.function(U1)(matrix(rnorm(45),15,3))

## Tensor cross-product is cross() or %X%:
U1 %X% U2
```

```
## A k-form is an alternating k-tensor:
K1 <- as.kform(cbind(1:5,2:6),rnorm(5))
K2 <- kform_general(3:6,2,1:6)
K3 <- rform(9,3,9,runif(9))

## The distributive law is true

(K1 + K2) ^ K3 == K1 ^ K3 + K2 ^ K3 # TRUE to numerical precision

## Wedge product is associative (non-trivial):
(K1 ^ K2) ^ K3
K1 ^ (K2 ^ K3)


## k-forms can be coerced to a function and wedge product:
f <- as.function(K1 ^ K2 ^ K3)

## E is a a random point in V^k:
E <- matrix(rnorm(63),9,7)

## f() is alternating:
f(E)
f(E[,7:1])



## The package blurs the distinction between symbolic and numeric computing:
dx <- as.kform(1)
dy <- as.kform(2)
dz <- as.kform(3)

dx ^ dy ^ dz

K3 ^ dx ^ dy ^ dz
```

`Alt` *Alternating multilinear forms*

Description

Converts a k-tensor to alternating form

Usage

```
Alt(S,give_kform)
```

Arguments

`S`	A multilinear form, an object of class `ktensor`
`give_kform`	Boolean, with default `FALSE` meaning to return an alternating k-tensor [that is, an object of class `ktensor` that happens to be alternating] and `TRUE` meaning to return a k-form [that is, an object of class `kform`]

Details

Given a k-tensor T, we have

$$\text{Alt}(T)\left(v_1,\ldots,v_k\right) = \frac{1}{k!}\sum_{\sigma\in S_k}\text{sgn}(\sigma)\cdot T\left(v_{\sigma(1)},\ldots,v_{\sigma(k)}\right)$$

Thus for example if $k=3$:

$$\text{Alt}(T)\left(v_1,v_2,v_3\right) = \frac{1}{6}\left(\begin{array}{ll} +T\left(v_1,v_2,v_3\right) & -T\left(v_1,v_3,v_2\right) \\ -T\left(v_2,v_1,v_3\right) & +T\left(v_2,v_3,v_1\right) \\ +T\left(v_3,v_1,v_2\right) & -T\left(v_3,v_2,v_1\right) \end{array}\right)$$

and it is reasonably easy to see that $\text{Alt}(T)$ is alternating, in the sense that

$$\text{Alt}(T)\left(v_1,\ldots,v_i,\ldots,v_j,\ldots,v_k\right) = -\text{Alt}(T)\left(v_1,\ldots,v_j,\ldots,v_i,\ldots,v_k\right)$$

Function `Alt()` is intended to take and return an object of class `ktensor`; but if given a `kform` object, it just returns its argument unchanged.

A short vignette is provided with the package: type `vignette("Alt")` at the commandline.

Value

Returns an alternating k-tensor. To work with k-forms, which are a much more efficient representation of alternating tensors, use `as.kform()`.

Author(s)

Robin K. S. Hankin

See Also

`kform`

Examples

```
S <- as.ktensor(expand.grid(1:3,1:3),rnorm(9))
S
Alt(S)

issmall(Alt(S) - Alt(Alt(S)))  # should be TRUE

a <- rtensor()
a
V <- matrix(rnorm(21),ncol=3)
c(as.function(Alt(a))(V), as.function(Alt(a,give_kform=TRUE))(V)) # should match
```

`as.1form` *Coerce vectors to 1-forms*

Description

Given a vector, return the corresponding 1-form; the exterior derivative of a 0-form (that is, a scalar function). Function `grad()` is a synonym.

Usage

```
as.1form(v)
grad(v)
```

Arguments

`v`	A vector with element i being $\partial f/\partial x_i$

Details

The exterior derivative of a k-form ϕ is a $(k+1)$-form $\mathbf{d}\phi$ given by

$$\mathbf{d}\phi\left(P_{\mathbf{x}}\left(\mathbf{v}_i,\ldots,\mathbf{v}_{k+1}\right)\right)=\lim_{h\longrightarrow 0}\frac{1}{h^{k+1}}\int_{\partial P_{\mathbf{x}}(h\mathbf{v}_1,\ldots,h\mathbf{v}_{k+1})}\phi$$

We can use the facts that

$$\mathbf{d}\left(f\,dx_{i_1}\wedge\cdots\wedge dx_{i_k}\right)=\mathbf{d}f\wedge dx_{i_1}\wedge\cdots\wedge dx_{i_k}$$

and

$$\mathbf{d}f=\sum_{j=1}^{n}\left(D_jf\right)\,dx_j$$

to calculate differentials of general k-forms. Specifically, if

$$\phi=\sum_{1\leq i_i<\cdots<i_k\leq n}a_{i_1\ldots i_k}dx_{i_1}\wedge\cdots\wedge dx_{i_k}$$

then

$$\mathbf{d}\phi=\sum_{1\leq i_i<\cdots<i_k\leq n}[\sum_{j=1}^{n}D_ja_{i_1\ldots i_k}dx_j]\wedge dx_{i_1}\wedge\cdots\wedge dx_{i_k}.$$

The entry in square brackets is given by `grad()`. See the examples for appropriate R idiom.

Value

A one-form

Author(s)

Robin K. S. Hankin

See Also

kform

Examples

```
as.1form(1:9)  # note ordering of terms


as.1form(rnorm(20))

grad(c(4,7)) ^ grad(1:4)
```

---

coeffs *Extract and manipulate coefficients*

Description

Extract and manipulate coefficients of ktensor and kform objects; this using the methods of the **spray** package.

Details

To see the coefficients of a `kform` or `ktensor` object, use `coeffs()`, which returns a `disord` object (this is actually `spray::coeffs()`). Replacement methods also use the methods of the **spray** package.

Author(s)

Robin K. S. Hankin

Examples

```
a <- kform_general(5,2,1:10)
coeffs(a) # a disord object
coeffs(a)[coeffs(a)%%2==1] <- 100  # replace every odd coeff with 100
```

consolidate *Various low-level helper functions*

Description

Various low-level helper functions used in `Alt()` and `kform()`

Usage

```
consolidate(S)
kill_trivial_rows(S)
include_perms(S)
kform_to_ktensor(S)
```

Arguments

S	Object of class `spray`

Details

Low-level helper functions.

- Function `consolidate()` takes a spray object, and combines any rows that are identical up to a permutation, respecting the sign of the permutation
- Function `kill_trivial_rows()` takes a spray object and deletes any rows with a repeated entry (which have k-forms identically zero)
- Function `include_perms()` replaces each row of a `spray` object with all its permutations, respecting the sign of the permutation
- Function `ktensor_to_kform()` coerces a k-form to a k-tensor

Value

The functions documented here all return a `spray` object.

Author(s)

Robin K. S. Hankin

See Also

`ktensor`,`kform`,`Alt`

Examples

```
S <- spray(matrix(c(1,1,2,2,1,3,3,1,3,5),ncol=2,byrow=TRUE),1:5)

kill_trivial_rows(S)  # (rows 1 and 3 killed, repeated entries)
consolidate(S)        # (merges rows 2 and 4)
include_perms(S)      # returns a spray object, not alternating tensor.
```

`contract` *Contractions of k-forms*

Description

A contraction is a natural linear map from k-forms to $k-1$-forms.

Usage

```
contract(K,v,lose=TRUE)
contract_elementary(o,v)
```

Arguments

`K`	A k-form
`o`	Integer-valued vector corresponding to one row of an index matrix
`lose`	Boolean, with default `TRUE` meaning to coerce a 0-form to a scalar and `FALSE` meaning to return the formal 0-form
`v`	A vector; in function `contract()`, if a matrix, interpret each column as a vector to contract with

Details

Given a k-form ϕ and a vector $\mathbf{v}$, the *contraction* $\phi_\mathbf{v}$ of ϕ and $\mathbf{v}$ is a $k-1$-form with

$$\phi_\mathbf{v}\left(\mathbf{v}^1,\ldots,\mathbf{v}^{k-1}\right)=\phi\left(\mathbf{v},\mathbf{v}^1,\ldots,\mathbf{v}^{k-1}\right)$$

provided $k>1$; if $k=1$ we specify $\phi_\mathbf{v}=\phi(\mathbf{v})$.

Function `contract_elementary()` is a low-level helper function that translates elementary k-forms with coefficient 1 (in the form of an integer vector corresponding to one row of an index matrix) into its contraction with $\mathbf{v}$.

There is an extensive vignette in the package, `vignette("contract")`.

Value

Returns an object of class `kform`.

Author(s)

Robin K. S. Hankin

References

Steven H. Weintraub 2014. “Differential forms: theory and practice”, Elsevier (Definition 2.2.23, chapter 2, page 77).

See Also

`wedge`,`lose`

Examples

```
contract(as.kform(1:5),1:8)
contract(as.kform(1),3)   # 0-form


## Now some verification [takes ~10s to run]:
#o <- kform(spray(t(replicate(2, sample(9,4))), runif(2)))
#V <- matrix(rnorm(36),ncol=4)
#jj <- c(
#   as.function(o)(V),
#   as.function(contract(o,V[,1,drop=TRUE]))(V[,-1]), # scalar
#   as.function(contract(o,V[,1:2]))(V[,-(1:2),drop=FALSE]),
#   as.function(contract(o,V[,1:3]))(V[,-(1:3),drop=FALSE]),
#   as.function(contract(o,V[,1:4],lose=FALSE))(V[,-(1:4),drop=FALSE])
#)

#print(jj)
#max(jj) - min(jj) # zero to numerical precision
```

`cross` *Cross products of k-tensors*

Description

Cross products of k-tensors

Usage

```
cross(U, ...)
cross2(U1,U2)
```

Arguments

`U,U1,U2`	Object of class `ktensor`
`...`	Further arguments, currently ignored

Details

Given a k-tensor S and an l-tensor T, we can form the cross product $S \otimes T$, defined as

$$S \otimes T\left(v_1, \ldots, v_k, v_{k+1}, \ldots, v_{k+l}\right) = S\left(v_1, \ldots v_k\right) \cdot T\left(v_{k+1}, \ldots v_{k+l}\right).$$

Package idiom for this includes `cross(S,T)` and `S %X% T`; note that the cross product is not commutative. Function `cross()` can take any number of arguments (the result is well-defined because the cross product is associative); it uses `cross2()` as a low-level helper function.

Value

The functions documented here all return a `spray` object.

Note

The binary form `%X%` uses uppercase X to avoid clashing with `%x%` which is the Kronecker product in base R.

Author(s)

Robin K. S. Hankin

References

Spivak 1961

See Also

`ktensor`

Examples

```
M <- cbind(1:4,2:5)
U1 <- as.ktensor(M,rnorm(4))
U2 <- as.ktensor(t(M),1:2)

cross(U1, U2)
cross(U2, U1)  # not the same!

U1 %X% U2 - U2 %X% U1
```

`hodge` *Hodge star operator*

Description

Given a k-form, return its Hodge dual

Usage

```
hodge(K, n=max(index(K)), g=rep(1,n), lose=TRUE)
```

Arguments

`K`	Object of class `kform`
`n`	Dimensionality of space, defaulting the the largest element of the index
`g`	Diagonal of the metric tensor, defaulting to the standard metric
`lose`	Boolean, with default `TRUE` meaning to coerce to a scalar if appropriate

Value

Given a k-form, in an n-dimensional space, returns a $(n-k)$-form.

Author(s)

Robin K. S. Hankin

See Also

wedge

Examples

```
hodge(rform())

hodge(kform_general(4,2),g=c(-1,1,1,1))


## Some edge-cases:
hodge(zero(5),9)
hodge(volume(5))
hodge(volume(5),lose=TRUE)
hodge(scalar(7),n=9)
```

---

inner *Inner product operator*

Description

The inner product

Usage

```
inner(M)
```

Arguments

M	square matrix

Details

The inner product of two vectors $\mathbf{x}$ and $\mathbf{y}$ is usually written $\langle\mathbf{x},\mathbf{y}\rangle$ or $\mathbf{x}\cdot\mathbf{y}$, but the most general form would be $\mathbf{x}^TM\mathbf{y}$ where M is a matrix. Noting that inner products are multilinear, that is $\langle\mathbf{x},a\mathbf{y}+b\mathbf{z}\rangle = a\langle\mathbf{x},\mathbf{y}\rangle + b\langle\mathbf{x},\mathbf{z}\rangle$ and $\langle a\mathbf{x}+b\mathbf{y},\mathbf{z}\rangle = a\langle\mathbf{x},\mathbf{z}\rangle + b\langle\mathbf{y},\mathbf{z}\rangle$, we see that the inner product is indeed a multilinear map, that is, a tensor.

Given a square matrix M, function `inner(M)` returns the 2-form that maps $\mathbf{x},\mathbf{y}$ to $\mathbf{x}^TM\mathbf{y}$.

A short vignette is provided with the package: type `vignette("inner")` at the commandline.

Value

Returns a k-tensor, an inner product

Author(s)

Robin K. S. Hankin

See Also

kform

Examples

```
inner(diag(7))
inner(matrix(1:9,3,3))

## Compare the following two:
Alt(inner(matrix(1:9,3,3)))      # An alternating k tensor
as.kform(inner(matrix(1:9,3,3))) # Same thing coerced to a kform

f <- as.function(inner(diag(7)))
X <- matrix(rnorm(14),ncol=2)  # random element of (R^7)^2
f(X) - sum(X[,1]*X[,2]) # zero to numerical precision

## verify positive-definiteness:
g <- as.function(inner(crossprod(matrix(rnorm(56),8,7))))
stopifnot(g(kronecker(rnorm(7),t(c(1,1))))>0)
```

---

issmall *Is a form zero to within numerical precision?*

Description

Given a k-form, return TRUE if it is "small"

Usage

```
issmall(M, tol=1e-8)
```

Arguments

M	Object of class kform or ktensor
tol	Small tolerance, defaulting to 1e-8

Value

Returns a logical

Author(s)

Robin K. S. Hankin

Examples

```
o <- kform_general(4,2,runif(6))
M <- matrix(rnorm(36),6,6)

discrepancy <- o - transform(transform(o,M),solve(M))

issmall(discrepancy)  # should be TRUE
is.zero(discrepancy)  # might be FALSE
```

keep — *Keep or drop variables*

Description

Keep or drop variables

Usage

```
keep(K, yes)
discard(K, no)
```

Arguments

`K`	Object of class `kform`
`yes,no`	Specification of dimensions to either keep (yes) or discard (no), coerced to a free object

Details

Function `keep(omega,yes)` keeps the terms specified and `discard(omega,no)` discards the terms specified. It is not clear to me what these functions mean from a mathematical perspective.

Value

The functions documented here all return a `kform` object.

Author(s)

Robin K. S. Hankin

See Also

`lose`

Examples

```
keep(kform_general(7,3),1:4)   # keeps only terms with dimensions 1-4
discard(kform_general(7,3),1)  # loses any term with a "1" in the index
```

kform *k-forms*

Description

Functionality for dealing with k-forms

Usage

```
kform(S)
as.kform(M,coeffs,lose=TRUE)
kform_basis(n, k)
kform_general(W,k,coeffs,lose=TRUE)
is.kform(x)
d(i)
## S3 method for class 'kform'
as.function(x,...)
```

Arguments

n	Dimension of the vector space $V = R^n$
i	Integer
k	A k-form maps V^k to R
W	Integer vector of dimensions
M,coeffs	Index matrix and coefficients for a k-form
S	Object of class spray
lose	Boolean, with default TRUE meaning to coerce a 0-form to a scalar and FALSE meaning to return the formal 0-form
x	Object of class kform
...	Further arguments, currently ignored

Details

A *k-form* is an alternating k-tensor. In the **stokes** package, k-forms are represented as sparse arrays (spray objects), but with a class of `c("kform","spray")`. The constructor function `kform()` takes a spray object and returns a kform object: it ensures that rows of the index matrix are strictly nonnegative integers, have no repeated entries, and are strictly increasing. Function `as.kform()` is more user-friendly.

- `kform()` is the constructor function. It takes a spray object and returns a kform.
- `as.kform()` also returns a kform but is a bit more user-friendly than `kform()`.
- `kform_basis()` is a low-level helper function that returns a matrix whose rows constitute a basis for the vector space $\Lambda^k(R^n)$ of k-forms.
- `kform_general()` returns a kform object with terms that span the space of alternating tensors.
- `is.kform()` returns TRUE if its argument is a kform object.
- `d()` is an easily-typed synonym for `as.kform()`

Recall that a k-tensor is a multilinear map from V^k to the reals, where $V = R^n$ is a vector space. A multilinear k-tensor T is *alternating* if it satisfies

$$T(v_1, \ldots, v_i, \ldots, v_j, \ldots, v_k) = T(v_1, \ldots, v_j, \ldots, v_i, \ldots, v_k)$$

In the package, an object of class `kform` is an efficient representation of an alternating tensor.

Function `kform_basis()` is a low-level helper function that returns a matrix whose rows constitute a basis for the vector space $\Lambda^k(R^n)$ of k-forms:

$$\phi = \sum_{1 \leq i_1 < \cdots < i_k \leq n} a_{i_1 \ldots i_k} dx_{i_1} \wedge \cdots \wedge dx_{i_k}$$

and indeed we have:

$$a_{i_1 \ldots i_k} = \phi\left(\mathbf{e}_{i_1}, \ldots, \mathbf{e}_{i_k}\right)$$

where $\mathbf{e}_j, 1 \leq j \leq k$ is a basis for V.

Value

All functions documented here return a `kform` object except `as.function.kform()`, which returns a function, and `is.kform()`, which returns a Boolean.

Note

Hubbard and Hubbard use the term “k-form”, but Spivak does not.

Author(s)

Robin K. S. Hankin

References

Hubbard and Hubbard; Spivak

See Also

`ktensor`,`lose`

Examples

```
as.kform(cbind(1:5,2:6),rnorm(5))
kform_general(1:4,2,coeffs=1:6)  # used in electromagnetism

K1 <- as.kform(cbind(1:5,2:6),rnorm(5))
K2 <- kform_general(5:8,2,1:6)
K1^K2  # or wedge(K1,K2)


f <- as.function(wedge(K1,K2))
E <- matrix(rnorm(32),8,4)
f(E) + f(E[,c(1,3,2,4)])  # should be zero by alternating property

options(stokes_symbolic_print = TRUE)
(d(5)+d(7)) ^ (d(2)^d(5) + 6*d(4)^d(7))
options(stokes_symbolic_print = FALSE)
```

ktensor *k-tensors*

Description

Functionality for k-tensors

Usage

```
ktensor(S)
as.ktensor(M,coeffs)
is.ktensor(x)
## S3 method for class 'ktensor'
as.function(x,...)
```

Arguments

`M,coeffs`	Matrix of indices and coefficients, as in `spray(M,coeffs)`
`S`	Object of class `spray`
`x`	Object of class `ktensor`
`...`	Further arguments, currently ignored

Details

A k-*tensor* object S is a map from V^k to the reals R, where V is a vector space (here R^n) that satisfies multilinearity:

$$S\left(v_1,\ldots,av_i,\ldots,v_k\right)=a\cdot S\left(v_1,\ldots,v_i,\ldots,v_k\right)$$

and

$$S\left(v_1,\ldots,v_i+{v_i}',\ldots,v_k\right)=S\left(v_1,\ldots,v_i,\ldots,x_v\right)+S\left(v_1,\ldots,{v_i}',\ldots,v_k\right).$$

Note that this is *not* equivalent to linearity over V^{nk} (see examples).

In the **stokes** package, k-tensors are represented as sparse arrays (`spray` objects), but with a class of `c("ktensor","spray")`. This is a natural and efficient representation for tensors that takes advantage of sparsity using **spray** package features.

Function `as.ktensor()` will coerce a k-form to a k-tensor via `kform_to_ktensor()`.

Value

All functions documented here return a `ktensor` object except `as.function.ktensor()`, which returns a function.

Author(s)

Robin K. S. Hankin

References

Spivak 1961

See Also

cross,kform,wedge

Examples

```
ktensor(rspray(4,powers=1:4))
as.ktensor(cbind(1:4,2:5,3:6),1:4)


## Test multilinearity:
k <- 4
n <- 5
u <- 3

## Define a randomish k-tensor:
S  <- ktensor(spray(matrix(1+sample(u*k)%%n,u,k),seq_len(u)))

## And a random point in V^k:
E <- matrix(rnorm(n*k),n,k)

E1 <- E2 <- E3 <- E

x1 <- rnorm(n)
x2 <- rnorm(n)
r1 <- rnorm(1)
r2 <- rnorm(1)

# change one column:
E1[,2] <- x1
E2[,2] <- x2
E3[,2] <- r1*x1 + r2*x2

f <- as.function(S)

r1*f(E1) + r2*f(E2) -f(E3) # should be small

## Note that multilinearity is different from linearity:
r1*f(E1) + r2*f(E2) - f(r1*E1 + r2*E2)  # not small!
```

Ops.kform *Arithmetic Ops Group Methods for* kform *and* ktensor *objects*

Description

Allows arithmetic operators to be used for k-forms and k-tensors such as addition, multiplication, etc, where defined.

Usage

```
## S3 method for class 'kform'
Ops(e1, e2 = NULL)
## S3 method for class 'ktensor'
Ops(e1, e2 = NULL)
```

Arguments

`e1,e2`	Objects of class `kform` or `ktensor`

Details

The functions `Ops.kform()` and `Ops.ktensor()` pass unary and binary arithmetic operators ("+", "-", "*", and "/") to the appropriate specialist function by coercing to `spray` objects.

For wedge products of k-forms, use `wedge()` or `%^%`; and for cross products of k-tensors, use `cross()` or `%X%`.

Value

All functions documented here return an object of class `kform` or `ktensor`.

Note

A plain asterisk, "*", given two ktensors, will return the cross product, on the grounds that the idiom has only one natural interpretation. But its use is discouraged.

In the package the caret ("^") evaluates the wedge product; note that `%^%` is also acceptable. Of course, if `S` is a `kform` object, it is very tempting to interpret "`S^3`" as something like "`S` to the power 3". Further, if we interpret a caret as a power, idiom such as "`2^S`" becomes meaningless.

But powers do not make sense for alternating forms: `a %^% a` is zero identically. Here the caret is interpreted consistently as a wedge product, and if one of the factors is numeric it is interpreted as a zero-form (that is, a scalar). Thus `a^2 == 2^a == a+a`, and indeed `a^n==a*n`.

Powers are not implemented for ktensors on the grounds that a ktensor to the power zero is not defined.

Author(s)

Robin K. S. Hankin

Examples

```
## dx_1 ^ dx_2 + 6dx_5 ^ dx_6:
as.kform(1) ^ as.kform(2) + 6*as.kform(5) ^ as.kform(6)

k1 <- kform_general(4,2,rnorm(6))
k2 <- kform_general(4,2,rnorm(6))

E <- matrix(rnorm(8),4,2)
as.function(k1+k2)(E)


as.function(2*k1+3*k2)(E)-(2*as.function(k1)(E) + 3*as.function(k1)(E))
## should be small
```

`print.stokes` *Print methods for k-tensors and k-forms*

Description

Print methods for objects with options for printing in matrix form or multivariate polynomial form

Usage

```
## S3 method for class 'kform'
print(x, ...)
## S3 method for class 'ktensor'
print(x, ...)
```

Arguments

`x`	k-form or k-tensor
`...`	Further arguments (currently ignored)

Details

The print method is designed to tell the user that an object is a tensor or a k-form. It prints a message to this effect (with special dispensation for zero tensors), then calls the `spray` print method.

Value

Returns its argument invisibly.

Note

The print method asserts that its argument is a map from R^n to R, where n is the largest element in the index matrix. However, such a map naturally furnishes a map from R^m to R provided that $m \geq n$ via the natural projection from R^n to R^m. Formally this would be $(x_1, \ldots, x_n) \mapsto (x_1, \ldots, x_n, 0, \ldots, 0) \in R^m$. In the case of the zero k-form or k-tensor, "n" is to be interpreted as "any $n \geq 0$".

By default, the print method uses the **spray** print methods, and as such respects the `polyform` option.

However, the print method is sensitive to the `stokes_symbolic_print` option. If `TRUE`, it uses `as.symbolic()` to give an alternate way of displaying k-forms.

Author(s)

Robin K. S. Hankin

See Also

`as.symbolic`

Examples

```
rform()
rtensor()

## spray print options work:
options(polyform = TRUE)
rtensor()


## reset to default
options(polyform = FALSE)
```

`rform` *Random kforms and ktensors*

Description

Random k-form objects and k-tensors, intended as quick "get you going" examples

Usage

```
rform(terms=9,k=3,n=7,coeffs)
rtensor(terms=9,k=3,n=7,coeffs)
```

Arguments

`terms`	Number of distinct terms
`k,n`	A k-form maps V^k to R, where $V = R^n$
`coeffs`	The coefficients of the form; if missing use `seq_len(terms)`

Details

What you see is what you get, basically.

Note that argument `terms` is an upper bound, as the index matrix might contain repeats which are combined.

Value

All functions documented here return an object of class `kform` or `ktensor`.

Author(s)

Robin K. S. Hankin

Examples

```
rform()
rform() %^% rform()

rtensor() %X% rtensor()

dx <- as.kform(1)
dy <- as.kform(2)
rform() ^ dx
rform() ^ dx ^ dy
```

`scalar` *Lose attributes*

Description

Scalars: 0-forms and 0-tensors

Usage

```
scalar(s,lose=FALSE)
is.scalar(M)
`0form`(s,lose=FALSE)
## S3 method for class 'kform'
lose(M)
## S3 method for class 'ktensor'
lose(M)
```

Arguments

`s`	A scalar value; a number
`M`	Object of class `ktensor` or `kform`
`lose`	In function `scalar()`, Boolean with `TRUE` meaning to return a normal scalar, and default `FALSE` meaning to return a formal 0-form or 0-tensor

Details

A k-tensor (including k-forms) maps k vectors to a scalar. If $k = 0$, then a 0-tensor maps no vectors to a scalar, that is, mapping nothing at all to a scalar, or what normal people would call a plain old scalar. Such forms are created by a couple of constructions in the package, specifically `scalar()`, `kform_general(1,0)` and `contract()`. These functions take a `lose` argument that behaves much like the `drop` argument in base extraction.

Function `lose()` takes an object of class `ktensor` or `kform` and, if of arity zero, returns the coefficient.

Note that function `kform()` *always* returns a `kform` object, it never loses attributes.

A 0-form is not the same thing as a zero tensor. A 0-form maps V^0 to the reals; a scalar. A zero tensor maps V^k to zero.

Value

The functions documented here return an object of class `kform` or `ktensor`, except for `is.scalar()`, which returns a Boolean.

Author(s)

Robin K. S. Hankin

See Also

`zeroform`,`lose`

Examples

```
o <- scalar(5)
o
lose(o)

kform_general(1,0)
kform_general(1,0,lose=FALSE)
```

`symbolic` *Symbolic form*

Description

Returns a character string representing k-tensor and k-form objects in symbolic form

Usage

```
as.symbolic(M,symbols=letters,d="")
```

Arguments

`M`	Object of class `kform` or `ktensor`; a map from V^k to R, where $V = R^n$
`symbols`	A character vector giving the names of the symbols
`d`	String specifying the appearance of the differential operator

Value

Returns a noquote character string.

Author(s)

Robin K. S. Hankin

See Also

`print.stokes`

Examples

```
as.symbolic(rtensor())
as.symbolic(rform())

as.symbolic(kform_general(3,2,1:3),d="d",symbols=letters[23:26])
```

`transform` *Linear transforms of k-forms*

Description

Given a k-form, express it in terms of linear combinations of the dx_i

Usage

```
transform(K,M)
stretch(K,d)
```

Arguments

K	Object of class `kform`
M	Matrix of transformation
d	Numeric vector representing the diagonal elements of a diagonal matrix

Details

Suppose we are given a two-form

$$\omega = \sum_{i<j} a_{ij} dx_i \wedge dx_j$$

and relationships

$$dx_i = \sum_r M_{ir} dy_r$$

then we would have

$$\omega = \sum_{i<j} a_{ij} \left(\sum_r M_{ir} dy_r \right) \wedge \left(\sum_r M_{jr} dy_r \right).$$

The general situation would be a k-form where we would have

$$\omega = \sum_{i_1<\cdots<i_k} a_{i_1\ldots i_k} dx_{i_1} \wedge \cdots \wedge dx_{i_k}$$

giving

$$\omega = \sum_{i_1<\cdots<i_k} \left[a_{i_1,\ldots,i_k} \left(\sum_r M_{i_1 r} dy_r \right) \wedge \cdots \wedge \left(\sum_r M_{i_k r} dy_r \right) \right].$$

The `transform()` function does all this but it is slow. I am not 100% sure that there isn't a much more efficient way to do such a transformation. There are a few tests in `tests/testthat` and a discussion in the `stokes` vignette.

Function `stretch()` carries out the same operation but for M a diagonal matrix. It is much faster than `transform()`.

Value

The functions documented here return an object of class `kform`.

Author(s)

Robin K. S. Hankin

References

S. H. Weintraub 2019. *Differential forms: theory and practice*. Elsevier. (Chapter 3)

See Also

`wedge`

Examples

```
# Example in the text:
K <- as.kform(matrix(c(1,1,2,3),2,2),c(1,5))
M <- matrix(1:9,3,3)
transform(K,M)

# Demonstrate that the result can be complicated:
M <- matrix(rnorm(25),5,5)
transform(as.kform(1:2),M)

# Numerical verification:
o <- rform(terms=2,n=5)

o2 <- transform(transform(o,M),solve(M))
max(abs(coeffs(o-o2))) # zero to numerical precision

# Following should be zero:
transform(as.kform(1),M)-as.kform(matrix(1:5),c(crossprod(M,c(1,rep(0,4)))))

# Following should be TRUE:
issmall(transform(o,crossprod(matrix(rnorm(10),2,5))))

# Some stretch() use-cases:

p <- rform()
p
stretch(p,seq_len(7))
stretch(p,c(1,0,0,1,1,1,1))   # kills dimensions 2 and 3
```

`volume` *The volume element*

Description

The volume element in n dimensions

Usage

```
volume(n)
is.volume(K)
```

Arguments

`n`	Dimension of the space
`K`	Object of class `kform`

Details

Spivak phrases it well (theorem 4.6, page 82):

If V has dimension n, it follows that $\Lambda^n(V)$ has dimension 1. Thus all alternating n-tensors on V are multiples of any non-zero one. Since the determinant is an example of such a member of $\Lambda^n(V)$ it is not surprising to find it in the following theorem:

Let $v_1,\ldots,v_n$ be a basis for V and let $\omega\in\Lambda^n(V)$. If $w_i=\sum_{j=1}^n a_{ij}v_j$ then

$$\omega\left(w_1,\ldots,w_n\right)=\det\left(a_{ij}\right)\cdot\omega\left(v_1,\ldots v_n\right)$$

(see the examples for numerical verification of this).

Neither the zero k-form, nor scalars, are considered to be a volume element.

Value

Function `volume()` returns an object of class `kform`; function `is.volume()` returns a Boolean.

Author(s)

Robin K. S. Hankin

References

Spivak

See Also

`zoroform`,`as.1form`

Examples

```
as.kform(1) ^ as.kform(2) ^ as.kform(3)  == volume(3)  # should be TRUE

o <- volume(5)
M <- matrix(runif(25),5,5)
det(M) - as.function(o)(M)   # should be zero
```

`wedge` *Wedge products*

Description

Wedge products of k-forms

Usage

```
wedge2(K1,K2)
wedge(x, ...)
```

Arguments

`K1,K2,x,...`	k-forms

Details

Wedge product of k-forms.

Value

The functions documented here return an object of class `kform`.

Note

In general use, use `wedge()` or `^` or `%^%`, as documented under `Ops`. Function `wedge()` uses low-level helper function `wedge2()`, which takes only two arguments.

A short vignette is provided with the package: type `vignette("wedge")` at the commandline.

Author(s)

Robin K. S. Hankin

See Also

`Ops`

Examples

```
k1 <- as.kform(cbind(1:5,2:6),1:5)
k2 <- as.kform(cbind(5:7,6:8,7:9),1:3)
k3 <- kform_general(1:6,2)

a1 <- wedge2(k1,wedge2(k2,k3))
a2 <- wedge2(wedge2(k1,k2),k3)

is.zero(a1-a2)  # NB terms of a1, a2 in a different order!

# This is why wedge(k1,k2,k3) is well-defined.  Can also use ^:
k1 ^ k2 ^ k3
```

---

zap *Zap small values in k-forms and k-tensors*

Description

Equivalent to `zapsmall()`

Usage

```
zap(X)
## S3 method for class 'kform'
zap(X)
## S3 method for class 'ktensor'
zap(X)
```

Arguments

X	Tensor or k-form to be zapped

Details

Given an object of class `ktensor` or `kform`, coefficients close to zero are 'zapped', i.e., replaced by '0', using `base::zapsmall()`.

Note, `zap()` actually changes the numeric value, it is not just a print method.

Value

Returns an object of the same class

Author(s)

Robin K. S. Hankin

Examples

```
S <- rform(7)
S == zap(S)
```

zero *Zero tensors and zero forms*

Description

Correct idiom for generating zero k-tensors and k-forms

Usage

```
zeroform(n)
zerotensor(n)
```

Arguments

n	Arity of the k-form or k-tensor

Value

Returns an object of class `kform` or `ktensor`.

Note

Idiom such as `as.ktensor(rep(1,n),0)` and `as.kform(rep(1,5),0)` and indeed `as.kform(1:5,0)` is incorrect as the arity of the tensor is lost.

A 0-form is not the same thing as a zero tensor. A 0-form maps V^0 to the reals; a scalar. A zero tensor maps V^k to zero.

Author(s)

Robin K. S. Hankin

See Also

scalar

Examples

```
as.ktensor(1+diag(5)) + zerotensor(5)
as.kform(matrix(1:6,2,3)) + zeroform(3)

## Following idiom is plausible but fails because as.ktensor(coeffs=0)
## and as.kform(coeffs=0) do not retain arity:

## Not run:
as.ktensor(1+diag(5)) +  as.ktensor(rep(1,5),0)   # fails
as.kform(matrix(1:6,2,3)) + as.kform(1:3,0)   # also fails

## End(Not run)
```

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