

Package ‘kimfilter’

October 13, 2022

Type Package

Title Kim Filter

Version 1.0.0

Date 2022-09-01

Description 'Rcpp' implementation of the multivariate Kim filter, which combines the Kalman and Hamilton filters for state probability inference. The filter is designed for state space models and can handle missing values and exogenous data in the observation and state equations. Kim, Chang-Jin and Charles R. Nelson (1999) "State-Space Models with Regime Switching: Classical and Gibbs-Sampling Approaches with Applications" <<http://econ.korea.ac.kr/~cjkim/doi:10.7551/mitpress/6444.001.0001>><<http://econ.korea.ac.kr/~cjkim/>>.

License GPL (>= 2)

Imports Rcpp (>= 1.0.9)

LinkingTo Rcpp, RcppArmadillo

RoxygenNote 7.2.1

Suggests data.table (>= 1.14.2), maxLik (>= 1.5-2), ggplot2 (>= 3.3.6), gridExtra (>= 2.3), knitr, rmarkdown, testthat

VignetteBuilder knitr

Encoding UTF-8

NeedsCompilation yes

Author Alex Hubbard [aut, cre]

Maintainer Alex Hubbard <hubbard.alex@gmail.com>

Depends R (>= 3.5.0)

Repository CRAN

Date/Publication 2022-09-14 06:00:05 UTC

R topics documented:

contains	2
gen_inv	2
kimfilter	3
kim_filter	3
Rginv	5
self_rbind	5
ss_prob	6
sw_dcf	7

Index	8
--------------	----------

contains	<i>Check if list contains a name</i>
----------	--------------------------------------

Description

Check if list contains a name

Usage

```
contains(s, L)
```

Arguments

s	a string name
L	a list object

Value

boolean

gen_inv	<i>Generalized matrix inverse</i>
---------	-----------------------------------

Description

Generalized matrix inverse

Usage

```
gen_inv(m)
```

Arguments

m	matrix
---	--------

Value

matrix inverse of m

kimfilter

Kim Filter

Description

kimfilter Rcpp implementation of the multivariate Kim filter, which combines the Kalman and Hamilton filters for state probability inference. The filter is designed for state space models and can handle missing values and exogenous data in the observation and state equations. `browseVignettes("kimfilter")` to view it in your browser.

Author(s)

Alex Hubbard

kim_filter

Kim Filter

Description

Kim Filter

Usage

```
kim_filter(ssm, yt, Xo = NULL, Xs = NULL, weight = NULL, smooth = FALSE)
```

Arguments

ssm	list describing the state space model, must include names B0 - $N_b \times 1$ matrix, initial guess for the unobserved components P0 - $N_b \times N_b$ matrix, initial guess for the covariance matrix of the unobserved components Dm - $N_b \times 1$ matrix, constant matrix for the state equation Am - $N_y \times 1$ matrix, constant matrix for the observation equation Fm - $N_b \times p$ matrix, state transition matrix Hm - $N_y \times N_b$ matrix, observation matrix Qm - $N_b \times N_b$ matrix, state error covariance matrix Rm - $N_y \times N_y$ matrix, state error covariance matrix betaO - $N_y \times N_o$ matrix, coefficient matrix for the observation exogenous data betaS - $N_b \times N_s$ matrix, coefficient matrix for the state exogenous data Pm - $n_{state} \times n_{state}$ matrix, state transition probability matrix
yt	$N \times T$ matrix of data
Xo	$N_o \times T$ matrix of exogenous observation data
Xs	$N_s \times T$ matrix of exogenous state
weight	column matrix of weights, $T \times 1$
smooth	boolean indication whether to run the backwards smoother

Value

list of cubes and matrices output by the Kim filter

Examples

```
#Stock and Watson Markov switching dynamic common factor
library(kimfilter)
library(data.table)
data(sw_dcf)
data = sw_dcf[, colnames(sw_dcf) != "dcoinc", with = FALSE]
vars = colnames(data)[colnames(data) != "date"]

#Set up the state space model
ssm = list()
ssm[["Fm"]] = rbind(c(0.8760, -0.2171, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0.0364, -0.0008, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, -0.2965, -0.0657, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0, 0, -0.3959, -0.1903, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -0.2436, 0.1281),
                   c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0))
ssm[["Fm"]] = array(ssm[["Fm"]], dim = c(dim(ssm[["Fm"]]), 2))
ssm[["Dm"]] = matrix(c(-1.5700, rep(0, 11)), nrow = nrow(ssm[["Fm"]]), ncol = 1)
ssm[["Dm"]] = array(ssm[["Dm"]], dim = c(dim(ssm[["Dm"]]), 2))
ssm[["Dm"]][1, 2] = 0.2802
ssm[["Qm"]] = diag(c(1, 0, 0, 0, 0.0001, 0, 0.0001, 0, 0.0001, 0, 0.0001, 0))
ssm[["Qm"]] = array(ssm[["Qm"]], dim = c(dim(ssm[["Qm"]]), 2))
ssm[["Hm"]] = rbind(c(0.0058, -0.0033, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0),
                   c(0.0011, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0),
                   c(0.0051, -0.0033, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0),
                   c(0.0012, -0.0005, 0.0001, 0.0002, 0, 0, 0, 0, 0, 0, 1, 0))
ssm[["Hm"]] = array(ssm[["Hm"]], dim = c(dim(ssm[["Hm"]]), 2))
ssm[["Am"]] = matrix(0, nrow = nrow(ssm[["Hm"]]), ncol = 1)
ssm[["Am"]] = array(ssm[["Am"]], dim = c(dim(ssm[["Am"]]), 2))
ssm[["Rm"]] = matrix(0, nrow = nrow(ssm[["Am"]]), ncol = nrow(ssm[["Am"]]))
ssm[["Rm"]] = array(ssm[["Rm"]], dim = c(dim(ssm[["Rm"]]), 2))
ssm[["B0"]] = matrix(c(rep(-4.60278, 4), 0, 0, 0, 0, 0, 0, 0, 0))
ssm[["B0"]] = array(ssm[["B0"]], dim = c(dim(ssm[["B0"]]), 2))
ssm[["B0"]][1:4, 2] = rep(0.82146, 4)
ssm[["P0"]] = rbind(c(2.1775, 1.5672, 0.9002, 0.4483, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(1.5672, 2.1775, 1.5672, 0.9002, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0.9002, 1.5672, 2.1775, 1.5672, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0.4483, 0.9002, 1.5672, 2.1775, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0.0001, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0.0001, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0.0001, -0.0001, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, -0.0001, 0.0001, 0, 0, 0, 0),
```

```

      c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0.0001, -0.0001, 0, 0),
      c(0, 0, 0, 0, 0, 0, 0, 0, 0, -0.0001, 0.0001, 0, 0),
      c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0.0001, -0.0001),
      c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -0.0001, 0.0001))
ssm[["P0"]] = array(ssm[["P0"]], dim = c(dim(ssm[["P0"]]), 2))
ssm[["Pm"]] = rbind(c(0.8406, 0.0304),
                   c(0.1594, 0.9696))

#Log, difference and standardize the data
data[, c(vars) := lapply(.SD, log), .SDcols = c(vars)]
data[, c(vars) := lapply(.SD, function(x){
  x - shift(x, type = "lag", n = 1)
}), .SDcols = c(vars)]
data[, c(vars) := lapply(.SD, scale), .SDcols = c(vars)]

#Convert the data to an NxT matrix
yt = t(data[, c(vars), with = FALSE])
kf = kim_filter(ssm, yt, smooth = TRUE)

```

Rginv

R's implementation of the Moore-Penrose pseudo matrix inverse

Description

R's implementation of the Moore-Penrose pseudo matrix inverse

Usage

```
Rginv(m)
```

Arguments

m matrix

Value

matrix inverse of m

self_rbind

Matrix self rowbind

Description

Matrix self rowbind

Usage

```
self_rbind(mat, times)
```

Arguments

mat	matrix
times	integer

Value

matrix

ss_prob	<i>Finds the steady state probabilities from a transition matrix mat = p_11 p_21 ... p_m1 p_12 p_22 ... p_m2 p_1m p_2m ... p_mm where the columns sum to 1</i>
---------	--

Description

Finds the steady state probabilities from a transition matrix mat = |p_11 p_21 ... p_m1| |p_12 p_22 ... p_m2| |... ...| |p_1m p_2m ... p_mm| where the columns sum to 1

Usage

```
ss_prob(mat)
```

Arguments

mat	square SxS matrix of probabilities with column sums of 1. S represents the number of states
-----	---

Value

matrix of dimensions Sx1 with steady state probabilities

Examples

```
library(kimfilter)
Pm = rbind(c(0.8406, 0.0304),
           c(0.1594, 0.9696))
ss_prob(Pm)
```

sw_dcf	<i>Stock and Watson Markov Switching Dynamic Common Factor Data Set</i>
--------	---

Description

Stock and Watson Markov Switching Dynamic Common Factor Data Set

Usage

```
data(sw_dcf)
```

Format

data.table with columns DATE, VARIABLE, VALUE, and MATURITY The data is monthly frequency with variables ip (industrial production), gmyxpg (total personal income less transfer payments in 1987 dollars), mtq (total manufacturing and trade sales in 1987 dollars), lpnag (employees on non-agricultural payrolls), and dcoinc (the coincident economic indicator)

Source

Kim, Chang-Jin and Charles R. Nelson (1999) "State-Space Models with Regime Switching: Classical and Gibbs-Sampling Approaches with Applications" <doi:10.7551/mitpress/6444.001.0001><<http://econ.korea.ac.kr/~c>

Index

* **datasets**

sw_dcf, 7

contains, 2

gen_inv, 2

kim_filter, 3

kimfilter, 3

Rginv, 5

self_rbind, 5

ss_prob, 6

sw_dcf, 7